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Anefficient weighted slime mould algorithm for engineering optimization

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Abstract

In engineering applications, optimal parameter design is crucial. While Slime Mould Algorithm (SMA) excels in parameter discovery under constrained conditions, it faces challenges in achieving global convergence and avoiding local opsecttimal traps in complex tasks. This paper introduces an enhanced variant of SMA, termed CCHSMA, which integrates a Chaotic Local Search (CLS) mechanism to improve initial population diversity and combines Covariance Matrix Adaptation (CMA) and Harris Hawks Optimization (HHO) strategies to enhance global search efficiency. CCHSMA aims to improve search quality and reduce the likelihood of getting trapped in local optima. We evaluated CCHSMA's effectiveness by benchmarking it against the standard SMA and its variants using 30 CEC2017 test functions, and compared its performance with seven notable meta-heuristic algorithms and ten advanced swarm intelligence variants. The experimental results demonstrate that CCHSMA outperforms the other algorithms tested on the benchmark functions. To further validate its practical utility, CCHSMA's performance was also benchmarked against leading algorithms in real-world engineering applications. This paper uses detailed statistical methods, including the Wilcoxon signed-rank test and the Friedman test, to validate the comparative results. Our fndings show that CCHSMA outperforms other algorithms in solving complex engineering optimization problems such as tension/compression spring design, pressure vessel design, and three-bar truss design, proving to be a robust tool for complex engineering optimization. Its enhanced initial population diversity and improved global search efficiency are essential for effectively addressing diverse engineering challenges.

Keywords: Slime mould algorithm, Engineering design, Swarm intelligence, Covariance matrix adaptation

Introduction

In practical applications, the efficacy of project design significantly influences construction and operational costs. As project scales expand, achieving high-quality, costefficient designs becomes increasingly vital. The design process involves formulating complex mathematical models with objectives, constraints, and various characteristics like discontinuity, nonlinearity, and nonconvexity. Researchers have explored diverse methods to address these challenges, each with unique strengths and limitations.

In mathematical modeling, Pucker et al. applied the SIMP method to geotechnical engineering, demonstrating topology optimization's potential and validating it through

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real-world cases [\[1](#page-32-0)]. Hsu et al. optimized the fuzzy proportional-diference controller using generalized fuzzy rules, proving its robustness and versatility in engineering design through variable monotonicity analysis [[2\]](#page-32-1). Herskovits et al. proposed numerical models for simultaneous analysis and design optimization and multidisciplinary design optimization, employing the feasible arc-in-point algorithm to reduce computational efort [\[3\]](#page-32-2). Sanchis et al. improved the normalized normal constraint method with an enhanced utopian hyperplane formulation, facilitating better Pareto boundary solution distribution in mechanical and structural design optimization [\[4](#page-32-3)].

In model automation, Esche et al. advanced chemical engineering models to automate simulation and optimization workfows [[5\]](#page-32-4). Li et al. leveraged cloud-based resources to decompose engineering optimization into interconnected sub-tasks, enhancing optimization, virtualization, and computational efficiency $[6]$ $[6]$.

Swarm intelligence algorithms are the core of this paper. Due to their computational efficiency and convergence to the optimal solution, they are very popular in many optimization fields such as networking $[7, 8]$ $[7, 8]$ $[7, 8]$ $[7, 8]$ $[7, 8]$, image segmentation $[9]$ $[9]$, the Internet of Things [[10–](#page-32-9)[12](#page-32-10)], economic emission [\[13,](#page-32-11) [14](#page-32-12)] and engineering design [\[15](#page-33-0)[–17](#page-33-1)]. In engineering optimization problem, Kashani et al. reviewed various swarm intelligence algorithms in structural engineering, providing benchmarking insights and comparing optimization techniques [\[18\]](#page-33-2). Singh et al. examined various aspects of engineering problems, including constraints, objectives, and variables, to facilitate problem-solving [[19\]](#page-33-3). Nasir et al. detailed water cycle algorithms and their applications across engineering felds [\[20](#page-33-4)]. Abualigah et al. categorized meta-heuristic optimization methods into basic, improved, and hybrid categories, reviewing their applications in engineering design [[21\]](#page-33-5).

Swarm intelligence algorithms, mimicking natural organisms' behavior, include Slime Mould Algorithm (SMA) [[22,](#page-33-6) [23](#page-33-7)], Particle Swarm Optimization (PSO) [[24](#page-33-8)], Salp Swarm Algorithm (SSA) [[25\]](#page-33-9), Bat Algorithm (BA) [\[26](#page-33-10)], Rime Optimization Algorithm (RIME) [\[27](#page-33-11)], Artifcial Bee Colony (ABC) [[28](#page-33-12)], Firefy Algorithm (FA) [[29](#page-33-13)], Colony Predation Algorithm (CPA) [\[30](#page-33-14)], Diferential Evolution (DE) [\[31](#page-33-15)], Harris Hawks Optimization (HHO) [[32\]](#page-33-16), Weighted Mean Of Vectors (INFO) [[33\]](#page-33-17), Grey Wolf Optimizer (GWO) [\[34](#page-33-18)], Polar Lights Optimization (PLO) [[35](#page-33-19)], Hunger Games Search (HGS) [[36\]](#page-33-20), Runge Kutta Optimizer (RUN) [\[37](#page-33-21)], Liver Cancer Algorithm (LCA) [[38](#page-33-22)], Artemisinin Optimization (AO) [[39](#page-33-23)], Fata Morgana Algorithm (FATA) [\[40](#page-33-24)], Parrot Optimizer (PO) [\[41](#page-33-25)], Educational Competition Optimizer (ECO) [[42](#page-33-26)], and Thermal Exchange Optimization (TEO) [\[43](#page-33-27)], and improved algorithms like Gaussian Barebone Harris Hawks Optimization (GBHHO) [[44\]](#page-33-28), Augmented Lagrange Constrained Particle Swarm Optimization (ALCPSO) [[45\]](#page-33-29), Simultaneous Sensor Calibration and Deformation Estimation (SCADE) [[46](#page-33-30)], Enhanced Grasshopper Optimization Algorithm (EGOA) [[47\]](#page-33-31). In practical applications, Sesok et al. optimized pile placement in mesh foundations using simulated annealing, demonstrating resource efficiency $[48]$ $[48]$ $[48]$. Akay et al. applied the ABC algorithm to various engineering problems, comparing it with other improved swarm intelligence algorithms [[49](#page-33-33)]. Wang et al. introduced the gravitational search strategy-assisted ride optimization algorithm for engineering design [[50\]](#page-33-34). Zhang et al. validated the improved sparrow searching whale optimization algorithm in engineering problems [\[51](#page-33-35)]. Arora et al. proposed the modifed butterfy optimization algorithm for mechanical optimization [[52](#page-33-36)]. Cheng et al. enhanced numerical search capabilities in structural algorithms with the fuzzy adaptive teaching–learning-based optimization algorithm [[53](#page-34-0)]. Ye et al. combined hybrid optimization with data mining in the sequential approximate optimization method for improved resource utilization [\[54](#page-34-1)]. Galvan et al. developed the predictive parameter pareto genetic algorithm for multi-objective optimization in magneto-fuidic thermal transport systems [[55\]](#page-34-2). Amir et al. utilized a sand cat swarm optimization algorithm to determine the direction and speed of motion through defned adaptive strategies, thereby achieving promising results in engineering optimization problems [[56\]](#page-34-3). Yang et al. used arithmetic optimization algorithm to combine two strategies, oppositionbased learning and the spiral modelling, in order to improve the global search and speed up the clustering of solutions at a later stage, and experiments showed that the algorithm performs well in engineering problems [[57](#page-34-4)]. Hijjawi et al. combined cuckoo search algorithm operators to enhance their search capability, the algorithm called AOACS, and applied it to engineering design problems [[58](#page-34-5)]. Hussien et al. optimized the beluga whale optimization using gaussian local mutation and transition factor strategies, demonstrating good performance in engineering design problems [[59](#page-34-6)]. Zhang et al. improved the honey badger algorithm using seven mathematical spirals with polar diameters and polar angles. It demonstrated better convergence performance while solving engineering design problems [[60](#page-34-7)]. Sait et al. combined swarm intelligence algorithm with artifcial neural networks have achieved more efective results in practical engineering problems [[61\]](#page-34-8).

Since the SMA was proposed, researchers in various felds have carried out relevant studies and made relevant progress. Mostafa et al. confrmed the extraction of photovoltaic cell parameters by using a SMA [\[62](#page-34-9)]. Gurses et al. compared four diferent algorithms including SMA and proposed the improved HSMA-SA for optimal value search for optimization problems [[63\]](#page-34-10). In the feld of wireless communications, Li et al. have proposed a novel binary slime mold optimization algorithm for the spectrum allocation model to address the spectrum allocation schemes [[64\]](#page-34-11). AlRassas et al. augmented the time-series model prediction with an improved ANFIS-SMAOLB as a means of predicting oil production [\[65\]](#page-34-12). Agarwal et al. proposed SMOA to shortest collision free path for robots to reduce the cost of time and money [[66\]](#page-34-13). Pawani et al. proposed a comprehensive learning wavelet-mutated SMA for fnding the optimal solution to the cogeneration scheduling problem with nonlinear and discontinuous constraints [\[67](#page-34-14)]. Peng et al. proposed the PDM-TSMA method to enhance the process of node localization within wireless sensor networks [[68](#page-34-15)].

However, SMA faces challenges such as prolonged search duration and diminished search ability over time, including difficulty in escaping local optima. To address these limitations, this paper introduces the Chaotic Covariance Harris Slime Mould Algorithm (CCHSMA), designed to improve convergence speed and optimal solution identifcation. CCHSMA integrates the Chaotic Local Search (CLS), Covariance Matrix Adaptation (CMA) [\[69\]](#page-34-16) and Harris Hawks Optimization (HHO) mechanisms. CLS enhances the quality of the initial population, CMA employs covariance computation with controlled step size, and HHO strengthens the mid-search process, synergistically enhancing SMA's performance.

The key contributions of this paper are as follows:

- Development of CCHSMA, an advanced version of the SMA, demonstrating enhanced search efficiency, local search capabilities, and the ability to avoid local optima.
- Performance evaluation of CCHSMA against leading swarm intelligence algorithms using the IEEE CEC2017 benchmarks, showcasing its superior efficacy.
- Application of CCHSMA in engineering design optimization, efectively translating real-world constraints into mathematical models, with successful implementation in the Tension/Compression Spring Design (TCSD), Pressure Vessel Design (PVD), and Three-Bar Truss Design (TBTD).

The experimental results validate CCHSMA's effectiveness in engineering optimization, highlighting its reliability and applicability. This paper is structured as follows: Section "[Background—SMA"](#page-3-0) introduces the fundamentals of SMA. Section "[Proposed](#page-5-0) [–CCHSMA method](#page-5-0)" elaborates on the CLS, CMA, and HHO mechanisms, explaining the framework's structure and rationale. Section ["Experiment design and results"](#page-10-0) compares CCHSMA with other prominent algorithms. Section "[Engineering problems](#page-25-0)" discusses CCHSMA's application in engineering design challenges. Section ["Conclusions](#page-31-0)" concludes with a summary of fndings and prospects for future research.

Background of the SMA

The SMA is modeled on the foraging behavior of slime moulds, particularly their complex movement patterns. Tis algorithm draws a analogy between slime mould foraging dynamics and optimization processes. During foraging, both the spatial distribution and the quantity of food significantly influence the slime mould's path. The distribution is infuenced not only by proximity but also by the quantity of food, with greater abundance exerting a stronger pull on the slime mould, efectively increasing its 'weight' in the decision-making process.

Slime moulds autonomously determine their actions by evaluating the food's quantity and density. If highly concentrated food sources are far from the slime mould, their infuence on its behavior diminishes. Three key processes encapsulate slime mould behavior, providing a basis for mathematical modeling of their foraging patterns.

Approaching food

The slime mould selects its foraging path by analyzing pheromones, leading to varied weighting in its decision-making process. Tis behavior is mathematically represented as follows:

$$
X(t+1) = \begin{cases} X_b(t) + vb \cdot (W \cdot X_A(t) - X_B(t)) & r < p \\ vc \cdot X(t) & r \ge p \end{cases} \tag{1}
$$

where $X(t)$ represents the current position generated by the slime mould at iteration t, X_b is the current population optimum, X_A and X_B represents two randomly selected solutions, and W denotes the weights influencing the foraging direction, r is a random value generated by a random function.

The probability p is determined by Eq. [\(2](#page-4-0)):

$$
p = \tanh \left| S(i) - bF \right| \tag{2}
$$

where *i* ranges from 1 to *n*, $S(i)$ denotes the fitness value of *X*, and *bF* is the best fitness value observed.

The equation of vb is defined in Eqs. ([3](#page-4-1)) and ([4\)](#page-4-2).

$$
vb = [-a, a] \tag{3}
$$

$$
a = \operatorname{arctanh}\left(-\left(\frac{t}{\max_{-} t}\right) + 1\right) \tag{4}
$$

where *max* t indicates the maximum number of iterations, and t represents the current number of iterations.

The value of vb operates within the range $[-a, a]$ and gradually converges to 0 as the number of iterations increases. Similarly, the variable vc , defined in Eqs. ([5\)](#page-4-3) and [\(6](#page-4-4)), oscillates between $[-b, b]$ and eventually converges to 0.

$$
vc = [-b, b] \tag{5}
$$

$$
b = 1 - \left(\frac{t}{\max_{\perp} t}\right) \tag{6}
$$

Wrapping food

This section models the slime mould's behavior in response to varying food qualities, introducing diferent levels of food quality as depicted in Eq. ([7\)](#page-4-5):

$$
X^* = \begin{cases} rand \cdot (UB - LB) + LB & rand < z \\ X_b(t) + vb \cdot (W \cdot X_A(t) - X_B(t)) & r < p \\ vc \cdot X(t) & r \ge p \end{cases} \tag{7}
$$

here, LB and UB represent the search space's lower and upper bounds, respectively. The variables *rand* and *r* are random values within the range $[0,1]$, and *z* is set to 0.03.

Finding food

The variable W , representing food concentration, indicates that higher values correspond to higher food concentrations, thus attracting the slime moulds more efectively. The weight W evolves with each iteration of the algorithm, adapting the attractiveness of the food. The formula for W is:

$$
W\left(SmellIndex\left(i\right)\right) = \begin{cases} 1 + r_1 \cdot \log\left(\frac{bF - S(i)}{bF - wF} + 1\right) & \text{condition} \\ 1 - r_1 \cdot \log\left(\frac{bF - S(i)}{bF - wF} + 1\right) & \text{other} \end{cases} \tag{8}
$$

$$
SmellIndex = sort(S) \tag{9}
$$

In Eqs. ([8\)](#page-4-6) and ([9\)](#page-4-7), SmellIndex represents a sorted array of ftness values derived from sorting S. bF and wF denote the best and worst fitness values, respectively. The variable r_1 is a random value within [0,1], and *condition* refers to the first half of the sequence values in $S(i)$.

Proposed SMA method

This section elaborates on optimizing the SMA to enhance its performance and generalizability.

Chaotic Local Search (CLS) mechanism

Efective initialization is a crucial aspect of optimization algorithms. Chaotic mapping, known for its unpredictability and non-repetitiveness, is a widely used method. It generates random numbers between 0 and 1, facilitating the exploration of diverse regions within the search space and accelerating convergence toward optimal solutions. We employ logistic mapping as a classic example of chaotic initialization, as defned in Eq. [\(10\)](#page-5-1).

$$
(t+1) = \mu X(t)(1 - X(t))t = 1, \cdots, n-1
$$
\n(10)

here, μ is the most important parameter, set to 4. t denotes the number of iterations, with $X(t)$ as the current solution and $X(t + 1)$ as the initialized result. Function test results indicate that the CLS mechanism's initialization signifcantly enhances experimental efficiency. However, due to reduced search capability in later stages, it necessitates the integration with other mechanisms, such as CMA, detailed subsequently.

Covariance Matrix Adaptation (CMA)

Covariance measures the correlation between two variables, and the covariance matrix represents these correlations across multiple dimensions of a multidimensional random variable, as shown in Eqs. (11) (11) and (12) :

$$
C = \begin{bmatrix} c_{11} & c_{12} & \dots & c_{1n} \\ c_{21} & c_{22} & \dots & c_{2n} \\ \dots & \dots & \dots & \dots \\ c_{n1} & c_{n2} & \dots & c_{nn} \end{bmatrix}
$$
(11)

here, c_{ij} representes the covariance (mixed central moment) between the i^{th} and j^{th} components of the *n*-dimensional variable $\overrightarrow{X} = (X_1, X_2, ..., X_n)$

$$
c_{ij} = Cov(X_i, X_j) = E\{ [X_i - E(X_i)] [X_j - E(X_j)] \}, i, j = 1, 2, ..., n
$$
\n(12)

Mutation targeting is facilitated by modifying the covariance matrix of the mutation distribution, increasing the probability of reproducing effective mutation steps. The rate of change is adjusted based on the number of strategy parameters. This adaptive mechanism operates independently of any specifc coordinate system. CMA constructs a mutation distribution with exponentially decreasing weights for selected mutations, leveraging past generations' selections to inform the direction and step size of new mutations. The distribution's overall variance and shape should be adjusted on different timescales. This approach mitigates the issue commonly encountered in swarm

intelligence algorithms, where optimal solutions may be located near suboptimal individuals.

The role of CMA in the algorithm can be delineated in three distinct steps:

1. The algorithm begins by generating random initial solutions, forming an overall population through a normal distribution centered around these solutions, as described by Eq. [\(13](#page-6-0)):

$$
X_i(t+1) \sim m(t) + \sigma(t) \cdot N(0, C(t)), i = 1, 2, \dots, \text{popsize}
$$
\n(13)

where X_i represents the i^{th} individual in the population, with i takes a range of integers from 1 to the population size (*popsize*). t denotes the current number of iterations, and *m* represents the center of mass of the population. σ is the step size. *N* is the multinomial normal distribution, and *C* is the $n \times n$ covariance matrix of the population, where *n* is the problem's dimensionality.

2. Tis step involves selecting a portion of the optimal solutions for future populations, based on the weighted average operation determined in Eqs. [\(14\)](#page-6-1) and ([15\)](#page-6-2):

$$
m(t + 1) = \sum_{i=1}^{\mu} \omega_i \cdot X_i(t + 1)
$$
 (14)

$$
\sum_{i=1}^{\mu} w_i = 1, w_1 \ge w_2 \ge \cdots \ge w_{\mu} > 0
$$
\n(15)

where μ is the number of selected parent populations, less than **popsize**, and w_i are the positive weights calculated from the previous generation, which sum to 1. $m(t + 1)$ becomes the center of mass for the next generation.

3. Determining the step size $\sigma(t)$ is crucial, as described in Eq. [\(16\)](#page-6-3):

$$
\sigma(t+1) = \sigma(t) \exp\left(\frac{c_{\sigma}}{d_{\sigma}} \left(\frac{P_{\sigma}(t+1)}{EN(0,I)} - 1\right)\right)
$$
(16)

Relevant parameters are detailed in Eq. ([17](#page-6-4)) to Eq. ([21](#page-7-0)):

$$
\mu_{\text{eff}} = \left(\sum_{i=1}^{\mu} w_i^2\right)^{-1} \tag{17}
$$

$$
c_{\sigma} = \frac{\mu_{\text{eff}} + 2}{n + \mu_{\text{eff}} + 5}, d_{\sigma} = 1 + 2\text{max}\left(0, \sqrt{\frac{\mu_{\text{eff}} - 1}{n + 1}} - 1\right) + c_{\sigma}
$$
(18)

here, μ_{eff} is variance effective selection mass, with $1 \leq \mu_{\text{eff}} \leq \mu$, and the evolutionary path $P_c(t)$ is given by:

$$
P_c(t+1) = (1 - c_1) \cdot P_c(t) + \sqrt{c_c \cdot (2 - c_c) \cdot \mu_{eff}} \left[\frac{m(t+1) - m(t)}{\sigma(t)} \right]
$$
(19)

Among them:

$$
c_c = \frac{4 + \mu_{\text{eff}}/n}{n + 4 + 2\mu_{\text{eff}}/n}
$$
\n
$$
\tag{20}
$$

$$
c_1 = \frac{2}{(n+1.3)^2 + \mu_{\text{eff}}}
$$
\n(21)

Exponential smoothing is employed for the construction of the evolutionary path and $p_c^{(0)} = 0$, leading to:

$$
p_c^{(t+1)} = (1 - c_c)p_c^{(t)} + \sqrt{c_c(2 - c_c)\mu_{\text{eff}}\frac{m^{(t+1)} - m^{(t)}}{\sigma^{(t)}}}
$$
(22)

Finally, the covariance matrix is updated as follows:

$$
\mathbf{C}(t+1) = (1 - c_1 - c_\mu) \cdot \mathbf{C}(t) + c_1 \cdot P_c(t+1) \n\cdot (P_c(t+1))^T + c_\mu \n\cdot \sum_{i=1}^{\mu} \omega_i \cdot \frac{(X_i(t+1) - m(t))}{\sigma(t)} \cdot \left(\frac{(X_i(t+1) - m(t))}{\sigma(t)}\right)^T
$$
\n(23)

$$
c_{\mu} = \min\left(1 - c_1, a_{\mu} \frac{\mu_{\text{eff}} - 2 + 1/\mu_{\text{eff}}}{(n+2)^2 + \alpha_{\mu} \mu_{\text{eff}}/2}\right) \text{with } \alpha_{\mu} = 2 \tag{24}
$$

The update process offers two options: one based on relative expectations within the parent generation, and the other based on expectations between successive generations.

Harris Hawks Optimization (HHO)

HHO is inspired by the cooperative hunting behavior of Harris Hawks in nature. It simulates their search and capture strategies, dynamically adapting to diferent environments. In the algorithm, the optimal solution represents the prey, with the iterative process of HHO mirroring the hawks' pursuit and capture strategies. HHO comprises two main phases: exploration and exploitation. The exploration phase involves two strategies for locating prey, while the exploitation phase uses four strategies for collaborative capture.

Exploration phase

The exploration phase in HHO employs equal probabilities for each search strategy, making them probabilistically equivalent for exploring different regions. The simulation incorporates the parameter q . The governing equations for this phase are as follows:

$$
X(t+1) = \begin{cases} X_{rand}(t) - r_1 | X_{rand}(t) - 2r_2 X(t) | & q \ge 0.5 \\ (X_{best}(t) - X_{mean}(t)) - r_3 (LB + r_4 (UB - LB)) & q < 0.5 \end{cases}
$$
(25)

$$
X_{mean}(t) = \frac{1}{N} \sum_{i=1}^{N} X_i(t)
$$
\n
$$
(26)
$$

When $q \ge 0.5$ the Harris Hawk searches randomly, when $q < 0.5$, it bases its search on the results from the previous generation. The iteration number is denoted by t , where $X(t)$ represents the population at the current iteration, and $X_{rand}(t)$ is the randomly selected location of the Harris Hawk in the t^{th} iteration. The term $|\cdot|$ represents the absolute value. $X_{best}(t)$ is the best solution found up to the current iteration. The parameters q , r 1, r 2, r 3, and r 4 are random values within the range [0,1]. $X_{mean}(t)$ is the average position of the current population, calculated as shown in Eq. [\(26](#page-8-0)).

Exploitation phase

In the HHO algorithm, once the Harris Hawk narrows down the prey's location, it employs four capture strategies: soft besiege, hard besiege, soft besiege with progressive rapid dives, and hard besiege with progressive rapid dives, adjusting the approach based on the prey's state.

The prey's condition is characterized by two parameters: escape energy (E) and escape probability (*r*). The prey's ability to escape is determined by $|E|$; if $|E| \ge 0.5$, it has sufficient energy to escape, whereas $|E|$ < 0.5 indicates a lack of energy. The escape probability is indicated by *r*, ranging from [0, 1], with $r \ge 0.5$ suggesting a failed escape and $r < 0.5$ indicating a successful escape. E is calculated as:

$$
E = 2E_0 \left(1 - \frac{t}{\max_{\perp} t} \right) \tag{27}
$$

where E_0 is a random number within [−1, 1], and E decays over iterations, reflecting the prey's weakening.

1. Soft besiege ($r \ge 0.5$ and $|E| \ge 0.5$):

Employing this strategy when the prey has enough energy but fails to escape, as shown in Eqs. [\(28](#page-8-1)) and ([29](#page-8-2)):

$$
X(t+1) = \Delta X(t) - E|JX_{\text{best}}(t) - X(t)|
$$
\n(28)

$$
\Delta X(t) = X_{\text{best}}(t) - X(t) \tag{29}
$$

where $\Delta X(t)$ is the difference between the hunter's and prey's positions, and *J* is a random number in [0, 2], indicating the prey's random motion intensity and varying between iterations.

2. Hard besiege ($r \ge 0.5$ and $|E| < 0.5$):

When the prey is exhausted, the hard besiege strategy is used, as per Eq. [\(30](#page-8-3)):

$$
X(t+1) = X_{\text{best}}(t) - E|\Delta X(t)|\tag{30}
$$

where E is calculated by Eq. ([27](#page-8-4)) and ΔX (t) is calculated by Eq. [\(29\)](#page-8-2).

3. Soft besiege with progressive rapid dives ($r < 0.5$ and $|E| \ge 0.5$):

Utilized when the prey is energetic and likely to escape. This strategy involves a combination of soft besiege and rapid dives, described in Eq. [\(31\)](#page-9-0) to Eq. ([34](#page-9-1)).

$$
Y = X_{\text{best}}(t) - E|JX_{\text{best}}(t) - X(t)|\tag{31}
$$

$$
Z = Y + S \times LF(D) \tag{32}
$$

$$
X(t+1) = \begin{cases} Y & \text{if } F(Y) < F(X(t)) \\ Z & \text{if } F(Z) < F(X(t)) \end{cases} \tag{33}
$$

$$
LF(x) = 0.01 \times \frac{\mu \times \sigma}{|\nu|^{\frac{1}{\rho}}}, \sigma = \left(\frac{\Gamma(1+\beta) \times \sin\left(\frac{\pi\beta}{2}\right)}{\Gamma\left(\frac{1+\beta}{2}\right) \times \beta \times 2^{\left(\frac{\beta-1}{2}\right)}}\right)^{\frac{1}{\rho}}
$$
(34)

where F is the fitness function, D denotes the problem's dimension, and S is a random vector bounded between 0 and 1. LF represents the Levy flight function, with μ and ν as random values between [0, 1], and β is typically set to 1.5.

4. Hard besiege with progressive rapid dives $(r < 0.5$ and $|E| < 0.5$):

Applied when prey has low energy but is cunning, the strategy follows Eq. [\(35\)](#page-9-2) to Eq. ([37](#page-9-3)):

$$
Y' = X_{\text{best}}(t) - E|X_{\text{best}}(t) - X_{\text{mean}}(t)|\tag{35}
$$

$$
Z' = Y' + S \times LF(D) \tag{36}
$$

$$
X(t+1) = \begin{cases} Y' & \text{if } F\left(Y^{Y'}\right) < F(X(t)) \\ Z' & \text{if } F\left(Z'\right) < F(X(t)) \end{cases} \tag{37}
$$

where $X_{mean}(t)$ represents the average position of the Harris Hawk in the current iteration, as calculated from Eq. ([26\)](#page-8-0).

Improved SMA framework components

The CCHSMA framework integrates various strategies, and its overall flowchart is depicted in Fig. [1.](#page-10-1) During the initialization phase, the population range is constrained. Recognizing the impact of initial results on the algorithm's search efficiency, a chaotic mechanism is applied to the initial population. This approach ensures a uniform distribution across the entire space, significantly enhancing search efficiency.

Fig. 1 Flowchart of CCHSMA

In the early stages, the SMA demonstrates efficient search capabilities, making it well-suited for iterative search and adaptation. However, as the search progresses into middle and late stages, SMA's efficiency declines. To address this, the CMA and HHO mechanisms are introduced to enhance exploration and exploitation. The experimental integration of SMA with CMA and HHO proves effective, improving the population's search capabilities and broadening the search scope. Additionally, it refines step size and search direction more systematically.

Experiment design and results

Tis section evaluates the performance of the CCHSMA method through experimental analysis. The benchmark functions from IEEE CEC2017 (referenced in Table [1\)](#page-11-0) are utilized to compare CCHSMA's performance against six SMA variants, seven fundamental metaheuristics, and six advanced swarm intelligence algorithms. Additionally, the algorithm's practical application is tested on engineering design problems. The experiments were conducted on a system with the following specifcations: Windows OS, 16 GB RAM, Intel(R) Core (TM) i5-10500 CPU at 3.10 GHz, using MATLAB R2019b.

Section ["Validation of the efectiveness of diferent mechanisms](#page-11-1)" examines the efects of various mechanisms on the SMA algorithm. Section ["Qualitative analysis of the improved](#page-12-0) [algorithm](#page-12-0)" demonstrates the qualitative analysis of CCHSMA. Section ["Comparison with](#page-16-0) [original swarm intelligence algorithms"](#page-16-0) focuses on validating CCHSMA's superior global search capability and its efectiveness in avoiding local optima, through comparisons with seven basic algorithms. Section ["Comparison with swarm intelligence algorithm variants](#page-17-0)" extends this comparative analysis to include six other advanced improved algorithms,

Table 1 30 Functions of IEEE CEC2017

ofering a comprehensive assessment of CCHSMA's performance in diverse scenarios. Section ["Comparative analysis of algorithms](#page-25-1)" verifes the robustness of the algorithm in diferent dimensions with diferent number of iterations.

Validation of the efectiveness of diferent mechanisms

In this study, a thorough comparison is conducted between the original SMA and its variants, including the CCHSMA, using IEEE CEC2017 benchmark functions at a 30-dimensional setting.

The variants examined are CMAHHOSMA, CLSHHOSMA, CLSCMASMA, CLSSMA, CMASMA, and HHOSMA. Each variant features a unique integration of mechanisms: CMAHHOSMA combines CMA and HHO without chaotic initialization, CLSCMASMA merges CLS and CMA excluding HHO, and CLSHHOSMA integrates CLS with HHO improvements. CLSSMA, CMASMA, and HHOSMA each apply distinct strategies to enhance SMA.

All algorithms and their variants are tested with a consistent population size of 30 and a maximum of 300,000 function evaluations (MaxFEs). Performance is measured by the mean (Avg.) and standard deviation (Std.) of optimal solutions, with Avg assessing global and local search capabilities, and Std evaluating robustness.

The IEEE CEC2017 functions are selected for testing CCHSMA, with additional statistical comparisons using Friedman's test. Tis analysis provides algorithm rankings based on their average performance across various functions. The results, along with a visual representation in Table [2](#page-13-0) and Fig. [2,](#page-16-1) underscore CCHSMA's superiority over other algorithms.

Notably, when CLS is used independently with SMA (e.g., in F4), it shows efective initialization but struggles to escape local optima in later stages. In contrast, CMASMA demonstrates stronger convergence later in the search process despite a less efective initialization phase compared to CLSSMA.

The addition of the enhanced HHO strategy is beneficial when CMA underperforms, as seen in F16, where the combination of various strategies leads to improved results. Similarly, in F15, CCHSMA maintains robust exploration even when other algorithms reach a convergence point. In F30, CCHSMA efectively utilizes the CLS mechanism for superior initialization, enhancing efficiency and reducing runtime.

The integration of the three mechanisms in CCHSMA effectively harnesses their individual strengths, resulting in a synergistic efect that surpasses the sum of their separate impacts. As indicated in Table [3](#page-16-2), CCHSMA ranks frst among its six variants and the original SMA, excelling in global search capability, robustness, and avoiding local optima. Therefore, CCHSMA emerges as the preferred and enhanced algorithm for optimization tasks.

Qualitative analysis of the improved algorithm

To elucidate the fundamental characteristics of the CCHSMA, this section undertakes a qualitative analysis of the algorithm with a focus on three dimensions: search trajectory, average ftness, and population equilibrium. In the provided Fig. [3,](#page-17-1) the frst column presents the three-dimensional functional graphs of the respective functions, indicating their general topographical features. The second column illustrates the spatiotemporal distribution of the search process, representing the spatial distribution of the population throughout the global search. The third column captures the evolution of the individuals' positions along the first dimension within the range of $[-100, 100]$. The fourth column quantifes the collective ftness level of the population.

In the visual representations, functions F1 and F4 demonstrate greater smoothness. As shown in column b, these functions quickly converge towards the vicinity of the optimal solution after initialization, facilitating further exploration. After several iterations, as shown in column c, these functions gradually converge to a specifc value for a focused search, ultimately reaching the optimal solution upon completing the iterative process.

Conversely, the search patterns for multimodal functions such as F6 and F10 are notably more complex. After initialization, the search trajectory exhibits continuous mutations and extensive exploration of potential solutions in various directions, avoiding entrapment in local minima. This dynamic is more clearly observed in column b.

Table 3 Friedman test of CCHSMA, CLSHHOSMA, CLSCMASMA, CMAHHOSMA, HHOSMA, CMASMA, CLSSMA and SMA on CEC2017 benchmark functions

		CCHSMA CLSHHOSMA CLSCMASMA CMAHHOSMA HHOSMA CMASMA CLSSMA SMA			
AVG 2.2333 4.3	5.6	23667	3 3.1666 5.2333 3.3667		
		RANK 1 6 8 2 3 4 7 5			

Comparison with original swarm intelligence algorithms

Tis section presents a detailed comparison of CCHSMA with well-known meta-heuristic algorithms, including SSA, BA, PSO, ABC, FA, DE, and HHO.

A comprehensive analysis of Table [4](#page-18-0) and Fig. [4](#page-21-0) indicates that CCHSMA outperforms its counterparts across most functions. It excels in initialization, achieving favorable positions from the start. For example, in function F30, the CLS mechanism signifcantly enhances initialization. The figure reveals that algorithms like PSO and BA are highly dependent on their initialization results, which strongly impact their fnal performance. During the middle exploration phase, as illustrated by F18, while other algorithms may demonstrate slower convergence, CCHSMA's integration of the HHO mechanism ensures rapid and efficient global search due to its advanced exploratory capabilities.

Fig. 3 a Illustration of functions, **b** Two-dimensional location distribution of CCHSMA, **c** Trajectory of CCHSMA in the frst dimension, **d** Average ftness of CCHSMA

Additionally, its use of segmented population classifcation further extends its scope and versatility.

The impact of the CMA mechanism on SMA is evident in function F12, where it improves the control over the search's depth and breadth. This enhancement leads to more reliable step generation and optimizes the algorithm's global search capabilities. The careful modulation of the influence from the parent generation ensures optimal utilization of the evolutionary path's length, resulting in signifcant performance improvements.

Post-evaluation, Table [5](#page-21-1) illustrates the rank averages and final standings, with CCHSMA consistently securing the top position. As highlighted in Table [5,](#page-21-1) CCHSMA not only outperforms other leading population-based intelligence algorithms but also consistently ranks at the top across all functions. It achieves top-tier scores in nearly all fundamental tests for each function, demonstrating its exceptional overall performance and superiority in diverse optimization scenarios.

Comparison with swarm intelligence algorithm variants

Tis section focuses on comparing the CCHSMA with advanced swarm intelligence optimization algorithm variants, namely OMGSCA [[70\]](#page-34-17), RDWOA [[71](#page-34-18)], EOBLSSA [\[72](#page-34-19)], GBHHO [\[44](#page-33-28)], GOTLBO [\[73](#page-34-20)], ALCPSO [\[45](#page-33-29)].

An analysis of the results in Table [6](#page-22-0) and Fig. [5](#page-24-0), particularly for function F1, reveals signifcant insights. While GOTLBO shows promising early-stage results and fast

Fig. 4 Convergence curves of CCHSMA and other MAs on CEC2017

Table 5 Friedman test of CCHSMA, SSA, PSO, BA, FA, DE, ABC and HHO on CEC2017 benchmark functions

	CCHSMA	SSA	BA	PSO	ABC	FA	DE	HHO
AVG	2.0333	3.9633	5.65	5.85	3.0683	7.24	3.565	4.63
RANK								

convergence, its performance declines over time, eventually reaching a stagnation point. In contrast, CCHSMA exhibits consistent convergence speed and stable progression throughout the iterations. Notably, in the later stages, CCHSMA avoids stagnation and engages efectively in local exploration, ultimately surpassing GOTLBO's performance.

Further examination of functions F3 and F12 highlights CCHSMA's sustained local exploration, even when other algorithms stabilize in later iterations. This persistent exploration allows CCHSMA to achieve optimal results by the end of the iteration process. This capability is particularly valuable for swarm intelligence algorithms in overcoming local optima. On the functions F1, F3, F4, F8, and F21, the CCHSMA algorithm has demonstrated its exceptional capability in local exploration and optimal solution identifcation, particularly as the algorithms approach the fnal stages of iterative convergence.

Fig. 5 Iteration curves of CCHSMA and other improved algorithms on CEC2017

Table 7 Friedman test of CCHSMA, OMGSCA, RDWOA, GBHHO, EOBLSSA, GOTLBO and ALCPSO on CEC2017 benchmark functions

	CCHSMA	OMGSCA	RDWOA	GBHHO	EOBLSSA	GOTLBO	ALCPSO
AVG	2.61333	491	4.79333	3.63667	484	2.94667	4.26
RANK			\sim	-3	h		Δ

The comparative performance of these algorithms, including CCHSMA, is summarized in Table [7](#page-24-1). In this comparison, CCHSMA achieves an average Friedman test result of 2.61333, ranking it highest overall. Although Fig. [5](#page-24-0) shows that certain functions, like F18, may perform better with other algorithms, the overall results in Table [7](#page-24-1) demonstrate CCHSMA's superior robustness and versatility. This robustness makes CCHSMA more adaptable to a variety of scenarios. In conclusion, CCHSMA not only improves the convergence capabilities of the original SMA but also broadens its application in tackling local convergence challenges. Throughout all functions, CCHSMA consistently outperforms its counterparts, including both basic algorithms and other advanced swarm intelligence options.

Comparative analysis of algorithms

In order to further demonstrate the robustness of the algorithms, we conducted additional comparative experiments, expanding the set of comparison algorithms from Section "Comparison with swarm intelligence algorithm variants" to include new algorithms such as XMACO [[74](#page-34-21)], LXMWOA [\[75\]](#page-34-22), SCBA [\[76](#page-34-23)], and QCSCA [[77\]](#page-34-24) for reference and comparison. These experiments were conducted using the IEEE CEC2017 test suite and were performed across 30, 50, and 100 dimensions at 300,000, 500,000, and 1,000,000 function evaluations, respectively. Tis expanded comparison aimed to analyze the strengths and weaknesses of each algorithm in diferent dimensional settings.

From Table [8](#page-26-0), it is evident that CCHSMA consistently ranks at the top across all dimensions and function evaluation counts, demonstrating its robustness. Figure [6](#page-27-0) illustrates that CCHSMA performs well throughout the entire process in the F1 test function. While some algorithms, such as GOTLBO, achieve faster convergence initially, CCHSMA excels in the fnal stages, overtaking others. Additionally, we can observe that with an increasing number of iterations, some algorithms demonstrate a strong ability to catch up. For instance, OMGSCA, which ranked 11th at 300,000 iterations, escapes local optima and rises to 4th place at 500,000 iterations, highlighting its capability to improve with extended iterations. Figure [7](#page-28-0) shows that CCHSMA excels particularly in achieving convergence, with its advantages becoming more apparent as the iteration count increases. Similarly, OMGSCA's performance improves with more iterations.

Engineering problems

In engineering, achieving accuracy and cost-efectiveness often begins with developing a precise mathematical model of the product. This section applies the CCHSMA to solve three engineering design problems: TCSD, PVD, and TBTD. These simulations incorporate a variety of constraints, including maximum-minimum, equation, boundary, and others, to fnd the optimal solution that meets the specifed requirements, ensuring the practicality of the results. CCHSMA is compared against other advanced meta-heuristic algorithms like SCADE, ALCPSO, BA, GWO, EGOA, ISSWOA [\[51](#page-33-35)], FDA [[78](#page-34-25)], EWOA [[79\]](#page-34-26), IGWO [[80\]](#page-34-27), HHO-PS [[81](#page-34-28)], hHHO-SCA [[82\]](#page-34-29), QL-ADIFA [\[83](#page-34-30)], ASOINU [\[84\]](#page-34-31), and MSFWA [\[85\]](#page-34-32).

Tension/Compression Spring Design (TCSD)

The objective in spring design encompasses meeting criteria for structure, performance, strength, and axial stability. The goal is to create springs that withstand significant working loads while maintaining their integrity under specifed operational conditions, particularly in high-pressure scenarios. Adapting the design to accommodate diferent materials and wire diameters is crucial for handling various force levels. In the TCSD problem, the primary objective is to minimize the weight of the spring.

The design parameters include the spring diameter (d) , center diameter (D) , number of active coils (n) , pitch (p) , and height (H) . The challenge lies in minimizing the spring weight while ensuring its functional efficacy. This involves optimizing a set of variables related to these parameters:

$$
Consider \vec{y} = [y_1 y_2 y_3] = [dDn]
$$
\n(38)

Fig. 6 Convergence curves for function evaluation of each algorithm for different dimensions with different number of iterations on the F1 function

The mathematical formulation of TCSD is as follows.

$$
\text{Minimize} f(\vec{y}) = (y_3 + 2)y_2 y_1^2 \tag{39}
$$

Subject to
$$
h_1(\vec{y}) = 1 - \frac{y_2^3 y_3}{71785 y_1^4} \le 0
$$
 (40)

$$
h_2(\vec{y}) = \frac{4y_2^2 - y_1y_2}{12566(y_2y_1^3 - y_1^4)} + \frac{1}{5180y_1^2} \le 0
$$
\n(41)

$$
h_3(\vec{y}) = 1 - \frac{140.45y_1}{y_2^3 y_3} \le 0
$$
\n(42)

$$
h_4(\vec{y}) = \frac{y_1 + y_2}{1.5} - 1 \le 0
$$
\n(43)

Variable range
$$
0.05 \le y_1 \le 2.00, 0.25 \le y_2 \le 1.30, 2.00 \le y_3 \le 15.0
$$
 (44)

Fig. 7 Convergence curves for function evaluation of each algorithm for different dimensions with different number of iterations on the F18 function

Equation [\(38](#page-25-2)) to Eq. ([44\)](#page-27-1) capture the complex interplay between the objective function, constraints, and variables in the TCSD problem. A comprehensive analysis and ranking within the same experimental framework were conducted.

Table [9](#page-28-1) showcases the superior performance of CCHSMA in resolving the TCSD challenge. The optimal solution obtained by CCHSMA is 0.012665233, with the optimal parameters being 0.051689061 for diameter (d) , 0.35671773 for center diameter (D), and 11.28896601 for the number of active coils (n) . These results highlight CCHSMA's exceptional global search capabilities in complex optimization scenarios, such as the TCSD problem.

Pressure Vessel Design (PVD)

Pressure vessels are critical in both industrial production and daily life. In their design phase, factors like material performance, force characteristics, and structural connections are considered to optimize costs, enhance quality, and minimize maintenance expenses. The goal is to minimize the total cost of cylindrical pressure vessel components. The key variables affecting cost include shell thickness (S) , head thickness (H) , inner radius (R) , and cross-sectional reduction range of the header (CH) .

The mathematical model for the Pressure Vessel Design (PVD) problem is expressed as follows:

$$
Consider \vec{y} = [y_1 y_2 y_3 y_4] = [SHRCH]
$$
\n(45)

$$
\text{Objective}: f(\vec{y})_{min} = 0.6224y_1y_3y_4 + 1.7781y_3y_1^2 + 3.1661y_4y_1^2 + 19.84y_3y_1^2 \tag{46}
$$

The restrictions are as follows:

$$
Subject to g_1(\vec{y}) = -y_1 + 0.0193y_3 \le 0,
$$
\n(47)

$$
g_2(\vec{y}) = -y_3 + 0.00954y_3 \le 0,\tag{48}
$$

$$
g_3(\vec{y}) = -\pi y_4 y_3^2 - \frac{4}{3}\pi y_3^3 + 1296000 \le 0
$$
\n(49)

$$
g_4(\vec{y}) = y_4 - 240 \le 0,\tag{50}
$$

The variables are restricted to:

 $0 \le y_1 \le 99,$ (51)

$$
0 \leq y_2 \leq 99,\tag{52}
$$

$$
10 \le y_3 \le 200,\tag{53}
$$

$$
10 \le y_4 \le 200. \tag{54}
$$

Using a similar analytical approach as in previous problems, this study compares the enhanced CCHSMA with other notable meta-heuristic algorithms. After rigorous testing for reliability, the results, presented in Table [10](#page-30-0), demonstrate CCHSMA's superior performance in solving the PVD problem.

The optimal solution obtained by CCHSMA is 6059.71445, with the variables shell thickness (S) , head thickness (H) , inner radius (R) , and cross-sectional reduction

range of the header (CH) being 0.8125, 0.4375, 42.09844474, and 176.6366069, respectively. These results highlight CCHSMA's robust local convergence capabilities in addressing this specifc type of engineering problem.

Three‑Bar Truss Design (TBTD)

The TBTD problem is a significant structural optimization challenge in engineering. Its primary objective is to minimize the weight of the structure while complying with constraints related to stress, defection, and buckling. A distinctive aspect of this problem is that two of the three bars must be of equal length, focusing attention on the lengths of these bars, denoted as l_1 and l_2 .

The mathematical formulation for the TBTD problem is as follows:

$$
Consider \vec{y} = [y_1 y_2] = [l_1 \cdot l_2]
$$
\n
$$
(55)
$$

Objective function:

$$
f(x) = \left(2\sqrt{2}y_1 + y_2\right) \times l \tag{56}
$$

Subject to:

$$
g_1(y) = \frac{\sqrt{2}y_1 + y_2}{\sqrt{2}y_1^2 + 2y_1y_2}P - \sigma \le 0
$$
\n(57)

$$
g_2(y) = \frac{y_2}{\sqrt{2}y_1^2 + 2y_1y_2}P - \sigma \le 0
$$
\n(58)

$$
g_3(y) = \frac{1}{\sqrt{2}y_2 + y_1}P - \sigma \le 0
$$
\n(59)

where:

$$
0 \le y_i \le 1i = 1, 2 \tag{60}
$$

$$
l = 100 \, \text{cm}, \, P = 2 \, \text{kN} / \, \text{cm}^2, \, \sigma = 2 \, \text{kN} / \, \text{cm}^2 \tag{61}
$$

Algorithm	Optimal values for variables	Optimum cost	
	y,	y ₂	
CCHSMA	0.788675137	0.408248283	263.8958434
SCADE	0.788390817	0.409099476	263.9005447
ALCPSO	0.633629429	0.815913922	263.8959534
BA	0.212348947	0.128496722	264.0147858
GWO	0.788606921	0.408441535	263.8958741
EGOA	0.788674445	0.40825024	263.8958434
IGWO (Li et al.,2021)	0.78846	0.40884	263.8959000
MSFWA (Han et al., 2020)	0.78867297	0.40825443	263.8958434
FDA (Karami et al2021)	0.788662	0.408286	263.8958430

Table 11 Comparison results of three-bar truss design problem between CCHSMA and other approaches

In the analysis of this design problem, a comparison of various swarm intelligence algorithms indicates that the CCHSMA stands out as the most optimal choice, delivering refned results. As shown in Table [11,](#page-31-1) the optimal solution achieved by CCHSMA is 263.8958434, with the corresponding variable values for l_1 and l_2 being 0.788675137 and 0.408248283, respectively. Tis comparison demonstrates that CCHSMA possesses robust local search capabilities, making it highly efective for this specifc type of engineering problem.

Conclusions

We introduce a novel variant of the SMA, termed CCHSMA, which exhibits robust capabilities for efficient search and controlled step size modulation, significantly improving its local search proficiency. The integration of the CLS strategy during initialization accelerates the identifcation of well-adapted populations, thereby enhancing search efficiency. Furthermore, the incorporation of an enhanced HHO mechanism bolsters global search capabilities. Additionally, the CMA mechanism is employed to calculate the covariance matrix, controlling step size and search direction, thereby aiding the algorithm in avoiding local optima. Results from IEEE CEC2017 benchmark functions underscore the robust global optimization potential of CCHSMA.

In engineering design optimization, CCHSMA has been applied to problems like Tension/Compression Spring Design, Pressure Vessel Design, and Three-Bar Truss Design. Mathematical models were developed for these cases, and experimental results demonstrate CCHSMA's profciency in designing products with enhanced precision by efectively utilizing constraint information. Tis results in improved product quality, enhanced performance, and reduced design cycles. Comparative analyses with other advanced algorithms affirm the robustness and effectiveness of CCHSMA, consistently achieving superior results across various problem types.

Although current experiments have achieved theoretical optima in some cases, deviations still exist in specific scenarios. The problem of local optimality has only been further optimized and not completely resolved, while the capability for global search can still be enhanced. Future research will categorize diferent classes of engineering problems to explore varied applications and evaluate the impact of distinct mechanisms on engineering results. The aim is to further understand and enhance CCHSMA's adaptability and performance across a wide range of engineering challenges. Furthermore, the integration of single-objective swarm intelligence optimization algorithms with multi-objective strategies or deep learning frameworks can address a wider range of engineering application problems.

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Author contributions

Qibo Sun: writing—original draft, writing—review & editing, software, visualization, investigation. Chaofan Wang: writing—original draft, writing—review & editing, software, visualization, investigation. Yi Chen: writing—original draft, writing—review & editing, software, visualization, investigation. Ali Asghar Heidari: writing—review & editing, software, visualization, investigation. Huiling Chen: conceptualization, methodology, formal analysis, investigation, writing review & editing, funding acquisition, supervision, project administration. Guoxi Liang: conceptualization, methodology, formal analysis, investigation, writing—review & editing, funding acquisition, supervision, project administration.

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Availability of data and materials

No datasets were generated or analysed during the current study.

Declarations

Ethics approval and consent to participate

Not applicable.

Consent for publication

All the author has read the journal policies and submit this manuscript in accordance with those policies.

Competing interests

The authors declare no competing interests.

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